

Deformation and the Change of Filtration Properties of Weaves - A Computational Approach

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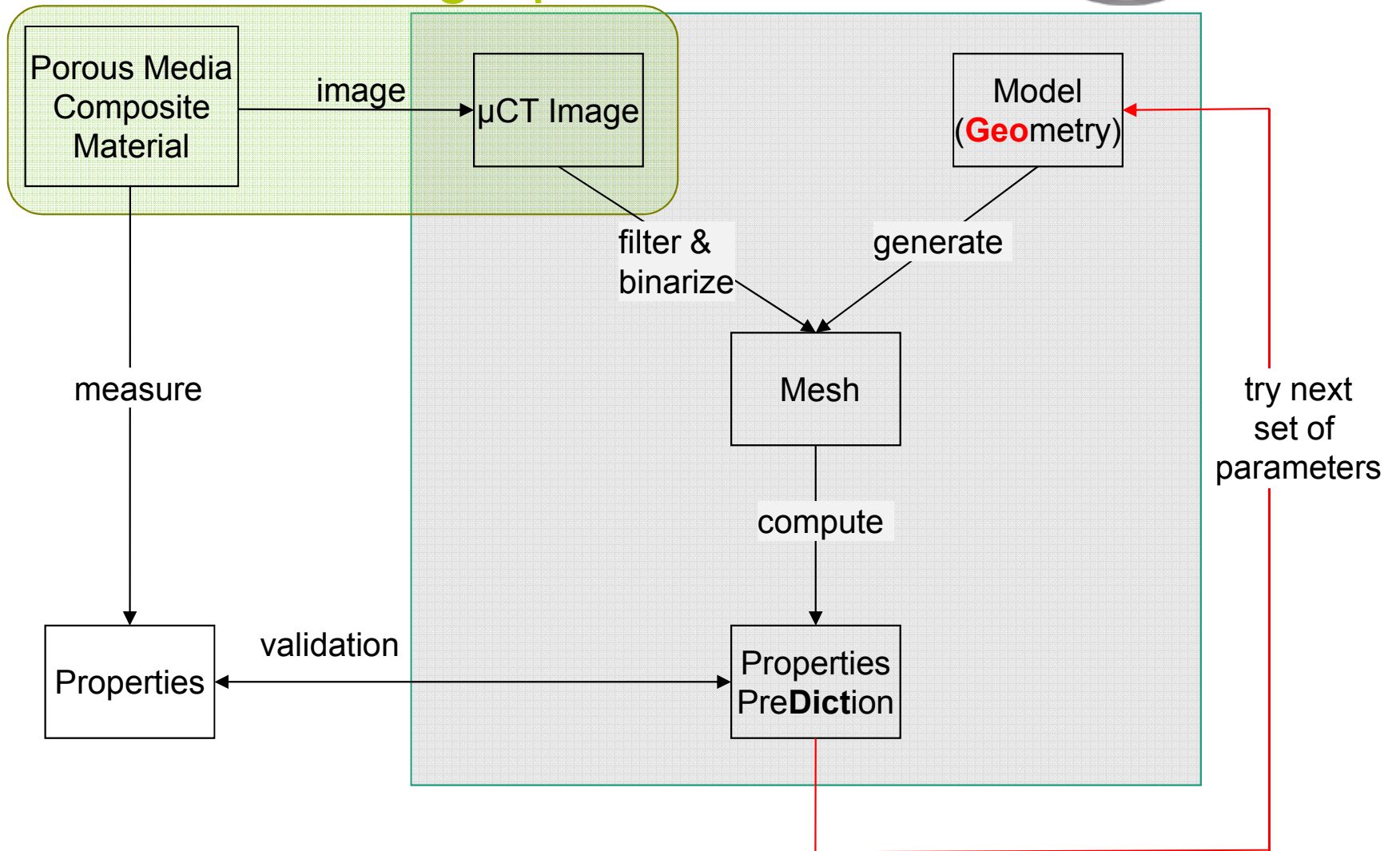
Outline

- Computing Material Properties with **GEO** DICT 
- Structure Generation - WeaveGeo
- CFD Simulation - FlowDict
- Filtration Simulation - FilterDict
- Structural Mechanics - FeelMath
- Results
- Conclusions

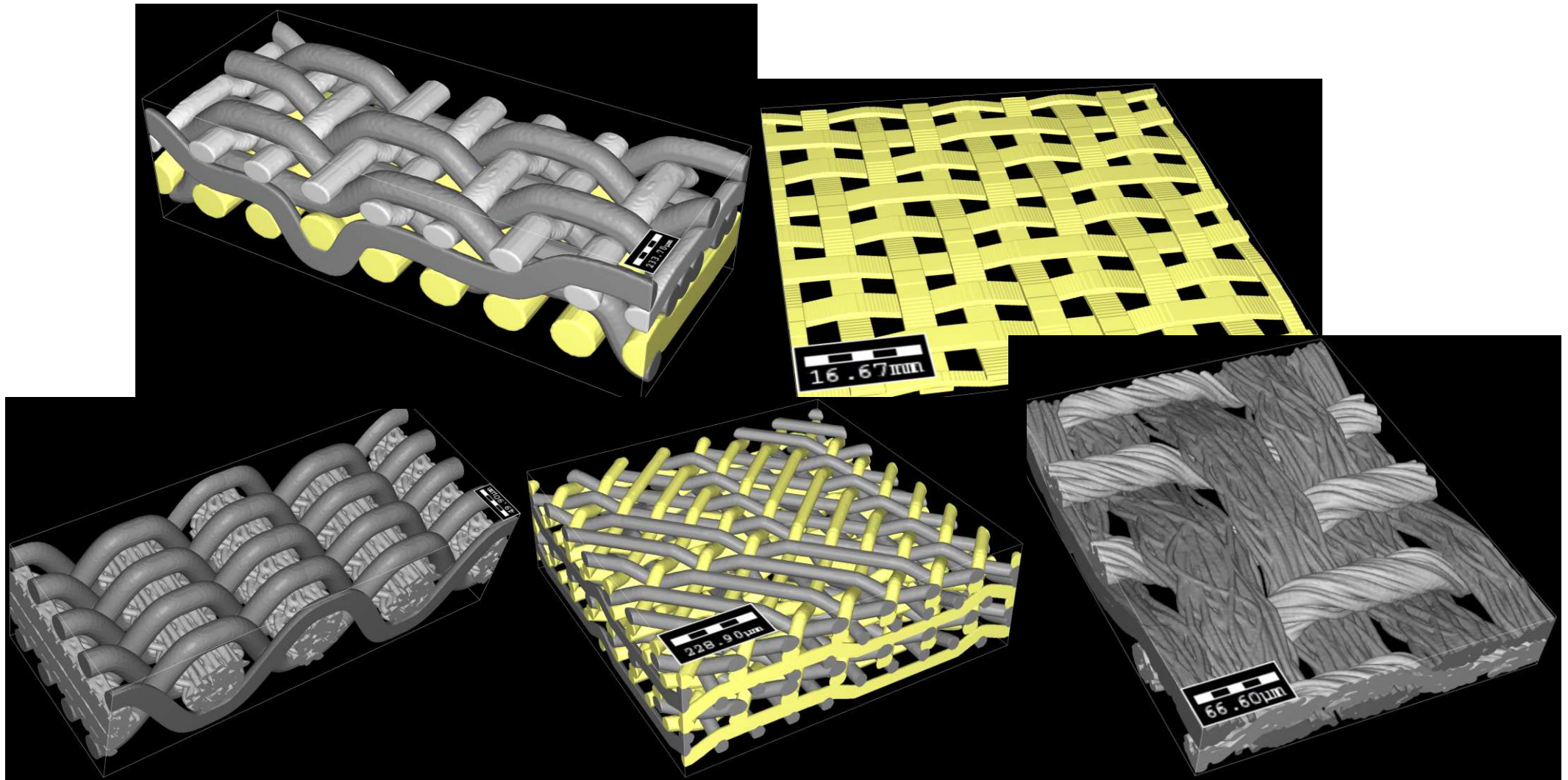
Computing Material Properties with GeoDict

GEO DICT

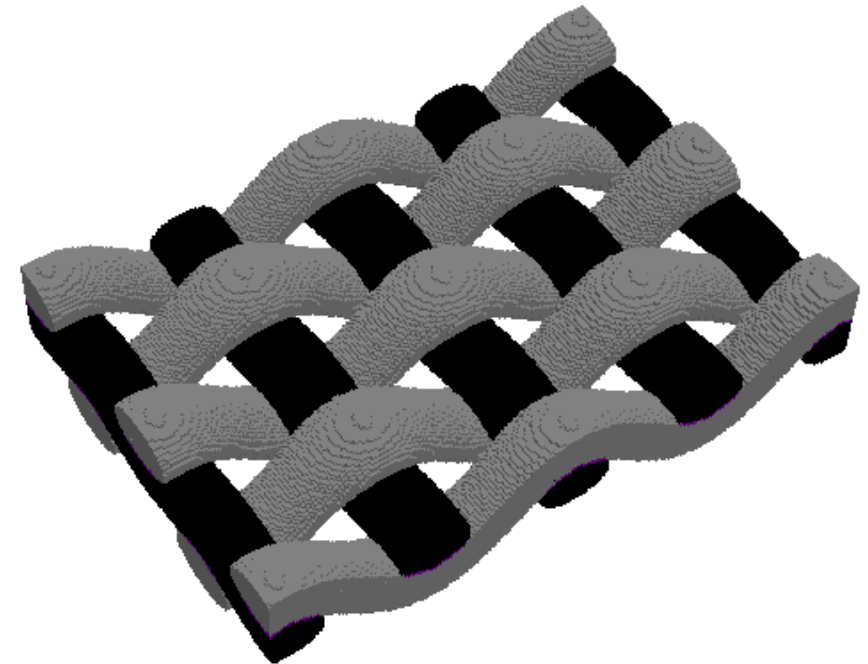
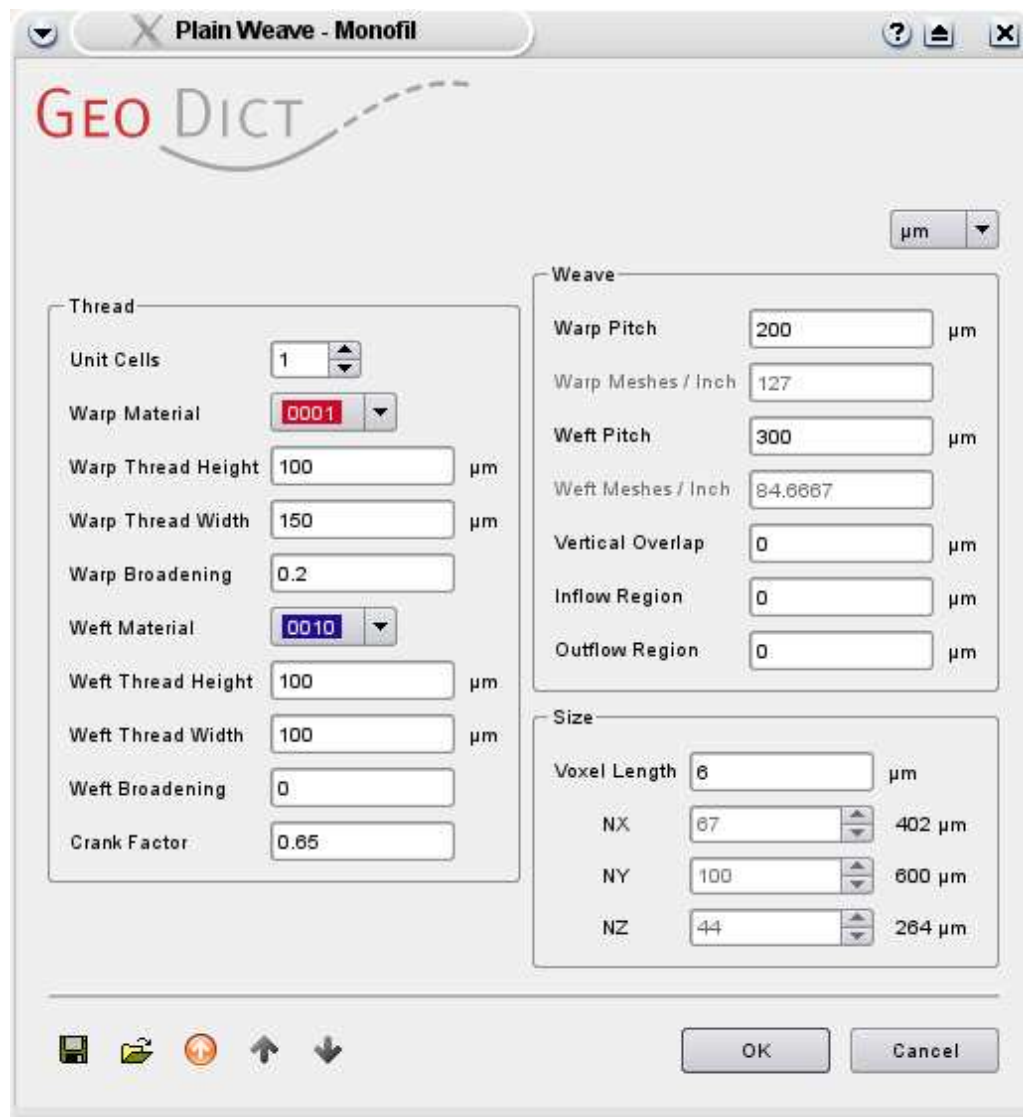
Tomograph



Structure Generation – WeaveGeo



Structure Generation – WeaveGeo



CFD Simulation - FlowDict

Navier-Stokes-Brinkman equations

$$-\mu \Delta \vec{u} + \nabla \vec{u} \cdot \vec{u} + \kappa^{-1} \vec{u} + \nabla p = \vec{f}, \quad (\text{momentum balance})$$
$$\nabla \cdot \vec{u} = 0, \quad (\text{continuity})$$

+ boundary conditions,

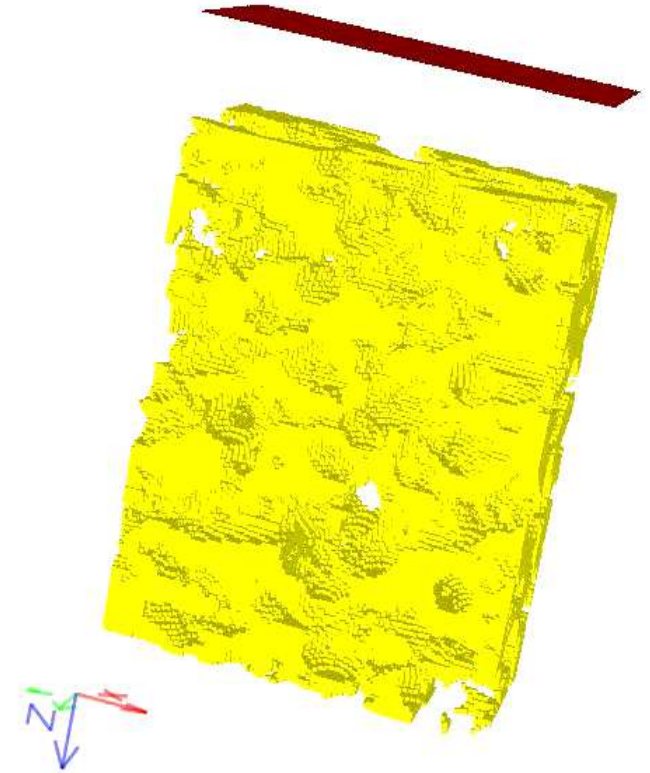
\vec{u} : velocity

p : pressure

\vec{f} : force (density)

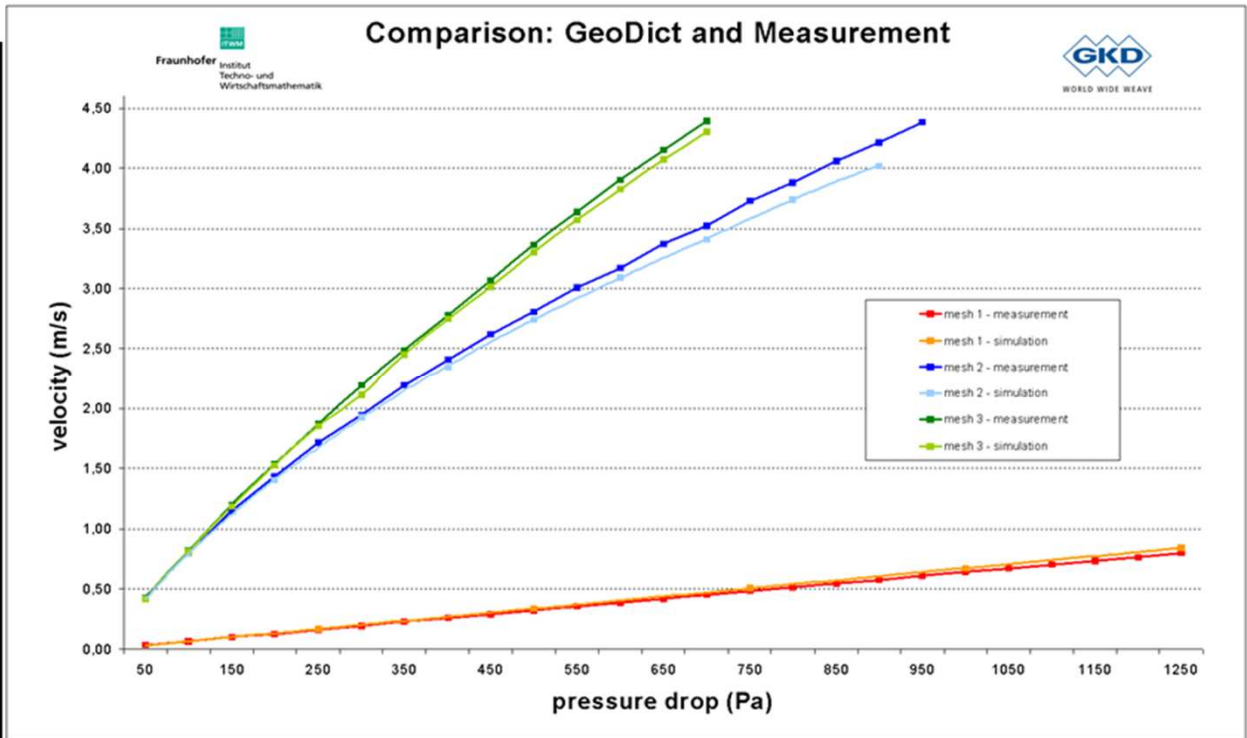
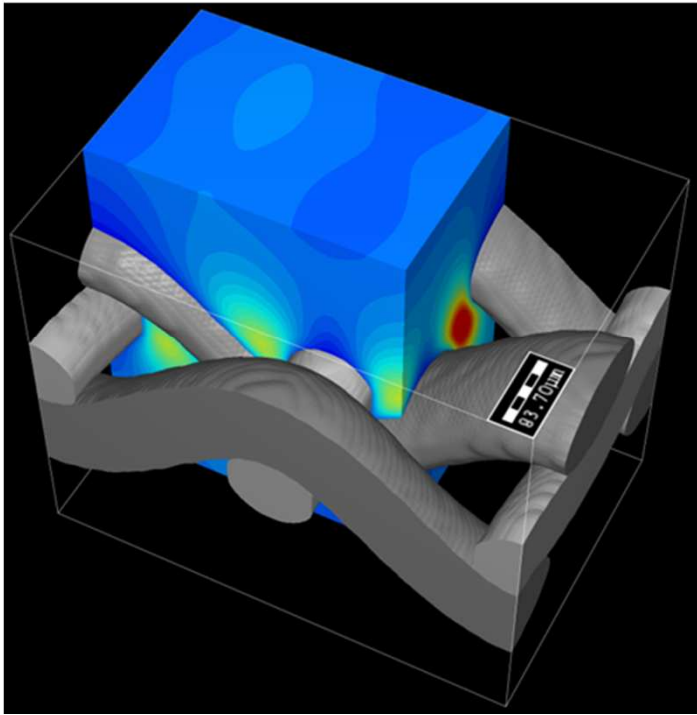
μ : fluid viscosity

κ : permeability of porous voxel

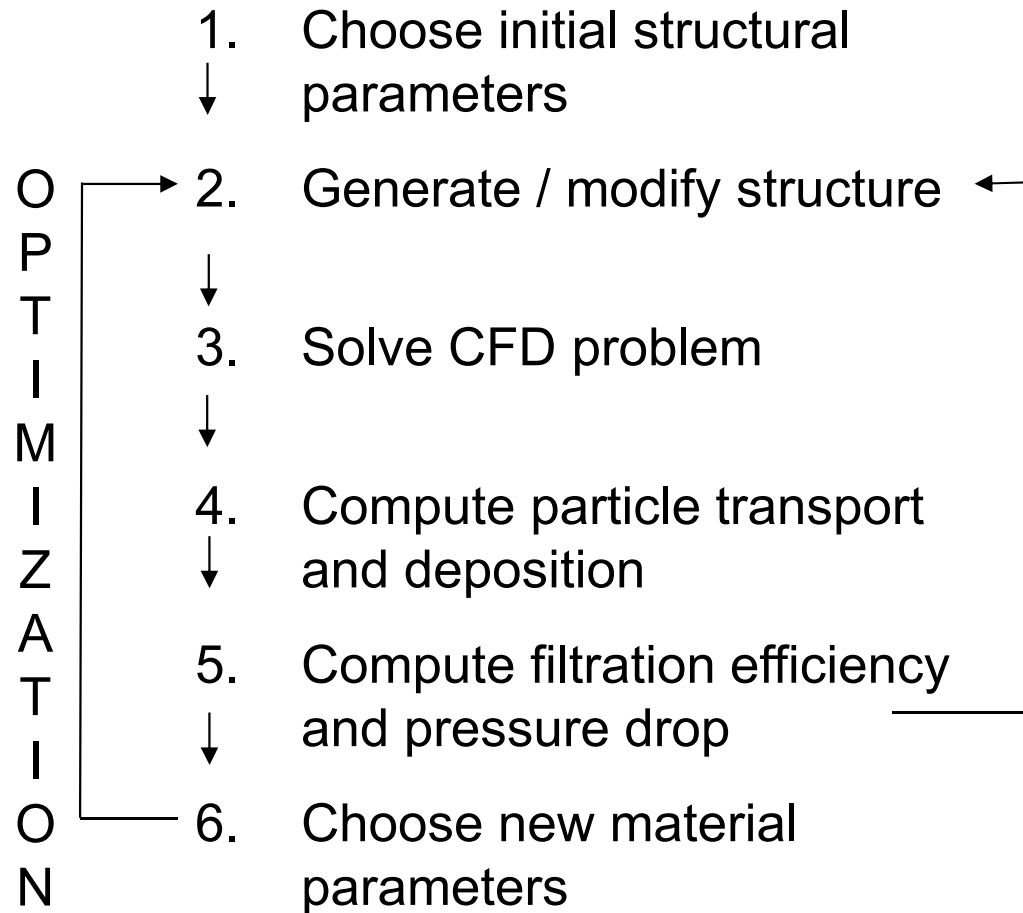


- Convective term -> optional for fast flows
- Brinkman term -> optional for porous media flows
- SIMPLE-type finite volume method optimized for huge voxel meshes

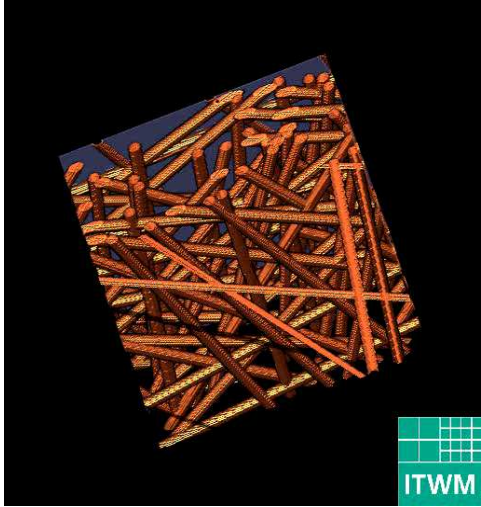
CFD Simulation - Validation



Filtration Simulation - FilterDict

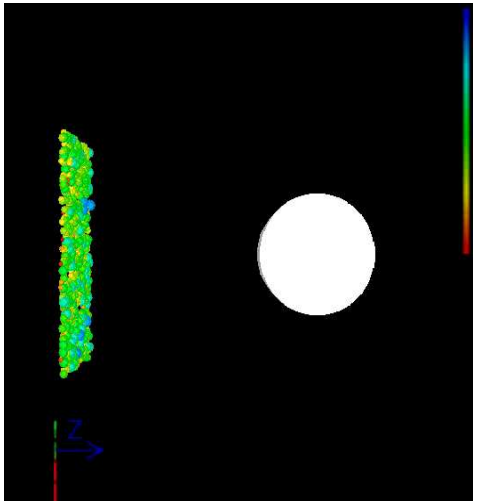


Flow



LIFETIME

Single Fiber Simulation



Filtration Simulation - FilterDict

Lagrangian Particle Transport

$$\frac{d\vec{x}}{dt} = \vec{v}$$
$$\frac{d\vec{v}}{dt} = -\gamma(\vec{v}(\vec{x}) - \vec{u}(\vec{x})) + \frac{Q\vec{E}_o(\vec{x})}{m} + \sigma \frac{d\vec{W}(t)}{dt}$$

Particle Deposition

- Collision handling
- Adhesion model

Modification of Geometry

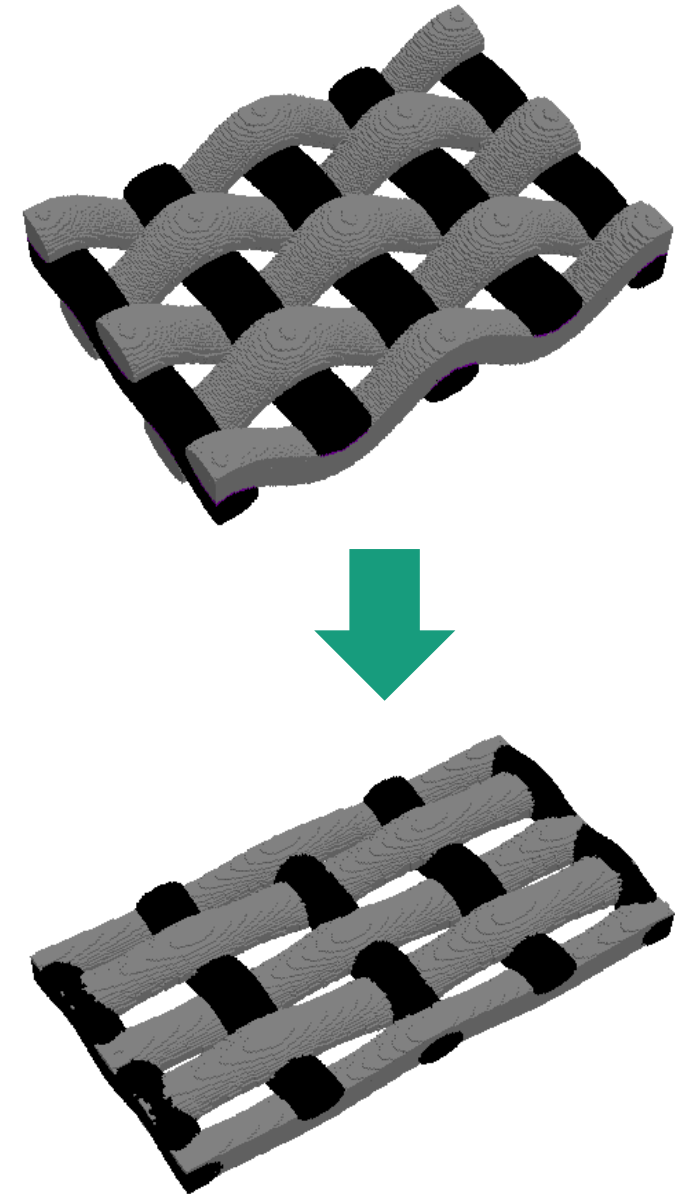
- Solid deposition model (particles resolved by voxels)
- Porous deposition model -> small particles are handled as porous media
- Porous deposition model + sub voxel collision handling

Structural Mechanics - FeelMath

- Use analytic description of fiber axis (GAD format)
- Use Simo beam theory [Simo85]
 - 6 degrees of freedom per node (3 displacements and 3 rotations)
 - Large displacements, rotations, and strains
- Introduce bond elements at crossing points as contact model
- Compute deformed structure
- Discretize to voxel mesh

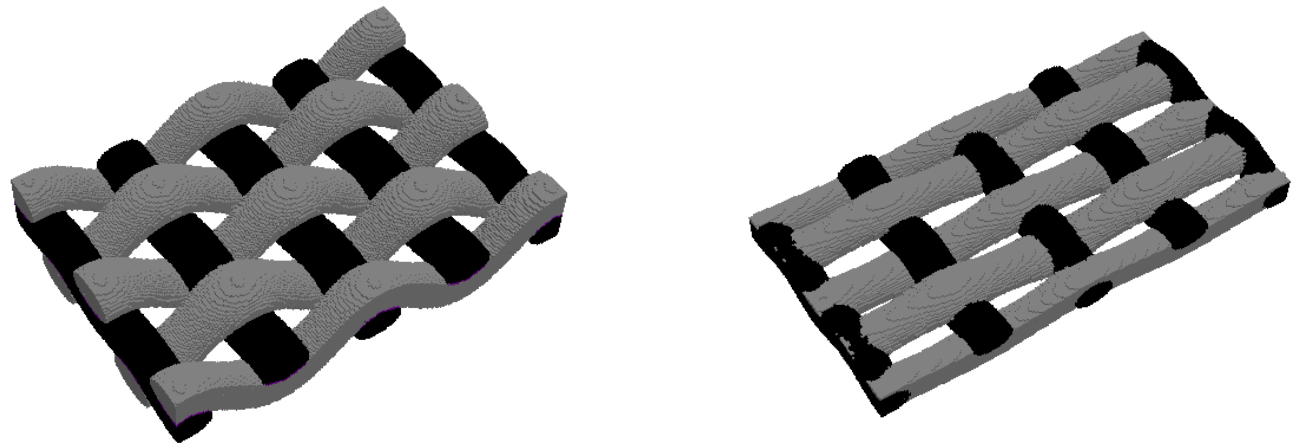
Current shortcomings

- Fibers may overlap after deformation
- Handling of cross-sections



Results - Deformation

- Use a plain weave
- Apply 30 % strain

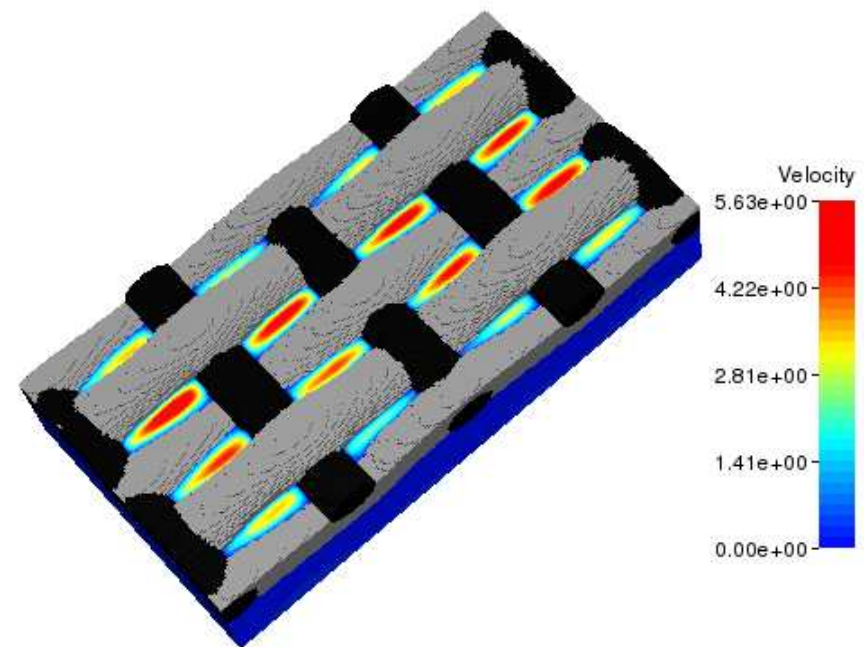
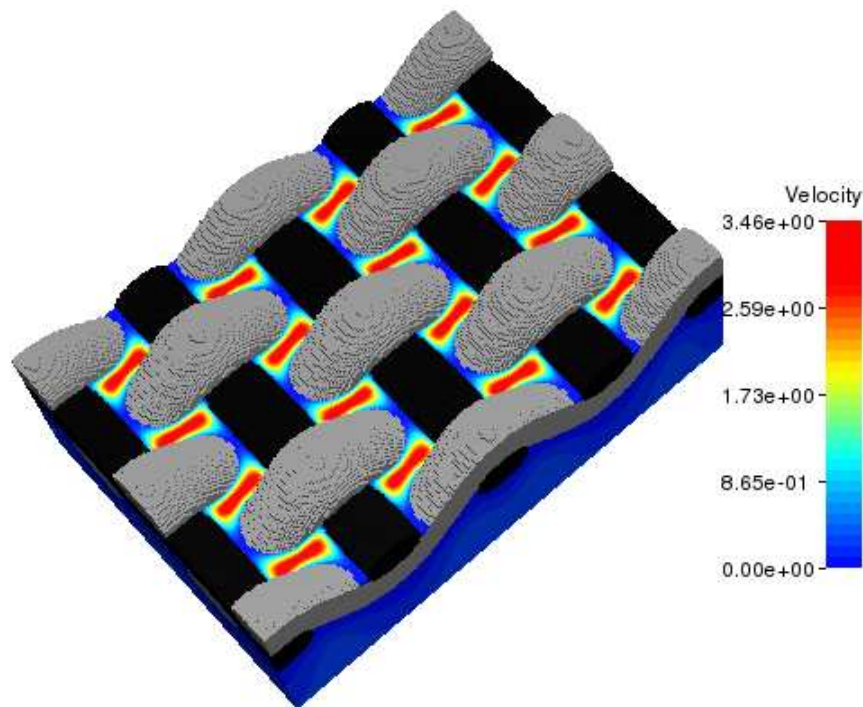


Geometrical observations

- Through pores initially being square developed a rectangular shape
- Maximum through pore diameter stays almost constant at 10 μm
- Medium is flattened

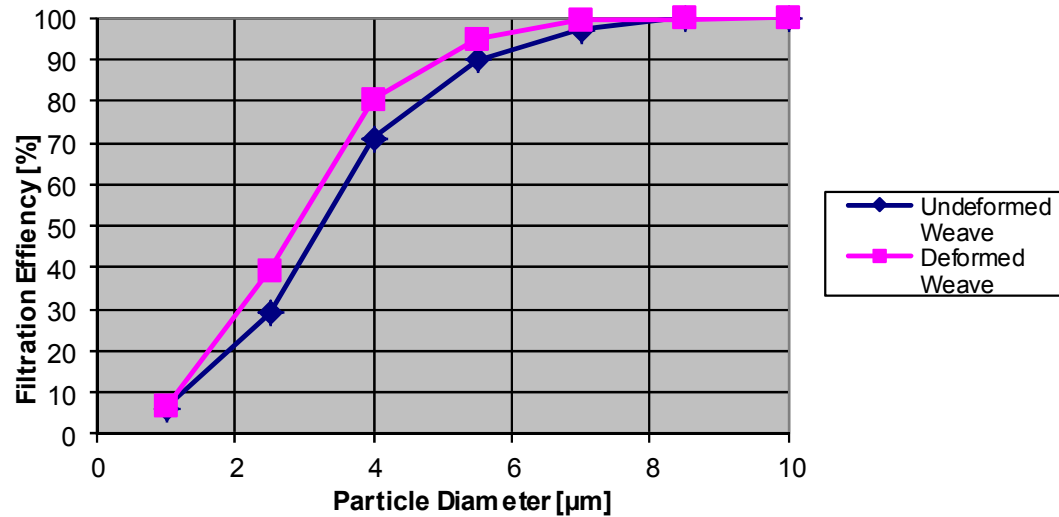
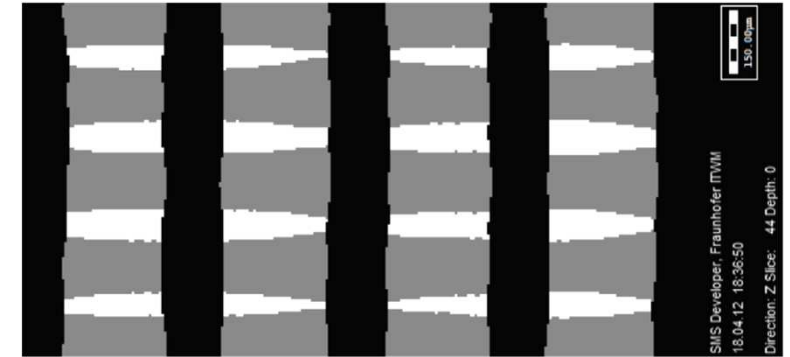
Results – CFD Simulation

- Apply pressure drop of 100 Pa across the medium
- Average velocity
 - undefomed case: 0.27 m/s
 - deformed case: 0.34 m/s

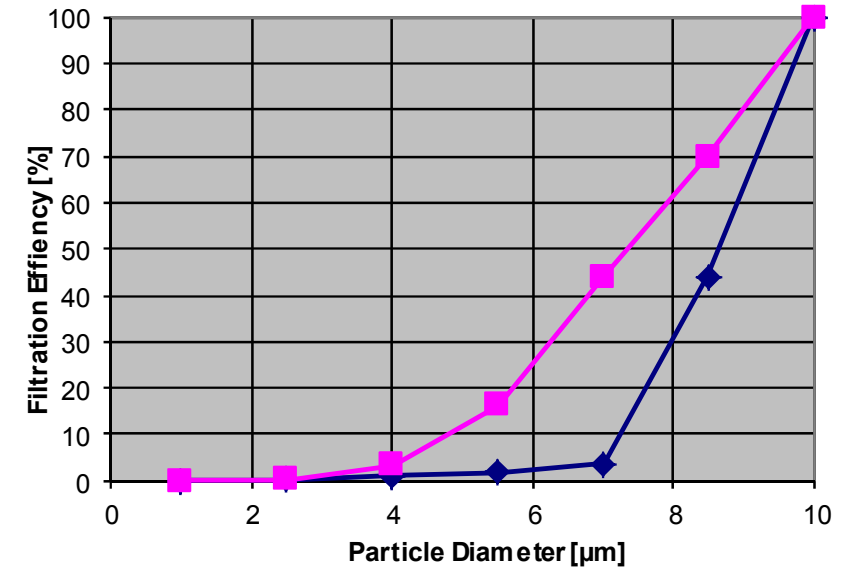


Results – Filtration Simulation

- Inflow velocity 0.1 m/s
- Compute initial filtration efficiencies



Caught On First Touch



Sieving

Conclusions

- A simulation framework for the microstructure simulation of weaves is developed.
- The single steps are performed by the Fraunhofer software GeoDict and the modules WeaveGeo, FlowDict, FilterDict and FeelMath.
- The simulation chain starts from a fully resolved woven. Deformation, fluid flow and particle filtration is then computed.
- The innovation of this work consists in the presentation of the new elasticity solver and its application to woven filter media.
- The results can be interpreted consistently within the model.
- Our future work will focus on
 - ❖ quantitative validation of the models
 - ❖ model refinements (overlap, cross-section handling)
 - ❖ transfer the methods to other fields of application

Thank You!



Geometry generator,
property predictor and
virtual material
designer

www.geodict.com

MATH
2 MARKET

